

ZED ready-toconnect low voltage servo drive

ZED is a ready-to-connect low voltage servo drive with an output current of up to 23A. Its small footprint enables spacesaving and near-motor mounting, fitting easily within the tight space constraints of applications such as electronics assembly, medical devices, and AGVs/AMRs.

Connectivity to PLC or modular safety controller

STO according to STO SIL3/PL e can be connected to a master motion PLC controller or to a modular safety controller. Two motor encoder signals A quad B RS422 can be daisy chained to the modular safety controller for Safe Motion monitoring, minimizing design complexity.

Master/slave communication

ZED to ZED real-time data exchange allows higher levels of axis synchronization and safer modes of operation.

Application examples

ZED drive is suited to stationary and mobile low voltage applications in the following industries:

- Intralogistics incl. AGV, AMR
- Medical Equipment
- Laboratory Automation
- Printing Machines
- Electronic Assembly & Semiconductor Equipment

Supporting multiple types of motor feedback

ZED drive supports a 12 bit and 4069 counts per revolution AqB incremental encoder, as well as Hall sensors and SSI. With STO functional safety the drive meets the full range of resolution and safe operation requirements from basic to highly dynamic applications.

Simple commissioning Motor Controller GUI with comprehensive parameterization options

Step-by-step guidance through the motor setup, application configuration and tuning process.



DRIVES

Key benefits

- High power density in a small footprint
- Ready-to-connect. No need for pin soldering or cable adaptors
- > STO functional safety (SIL 3/PL e)
- Supports AqB encoder, Hall sensors and SSI-encoders
- Meets the full range of resolution and safe operation requirements
- Near-motor mounting for tight space constraints applications
- Simple commissioning GUI with comprehensive parameterization options
- > CE and cUL certifications



| | Model | Input bus (VDC) | Input logic (VDC) | Cont. current (Arms) | Cont. current with heat sink (Arms) | Peak current (Arms) |
|---------------|----------|--------------------|----------------------|-------------------------|--|------------------------|
| Anna and Anna | SD01-015 | 24 | 24 | 12 | 14.4 | 40 |
| | SD01-030 | 24 | 24 | 20 | 23 | 70 |
| | SD01-025 | 48 | 24 | 18 | 20 | 63 |

Communications:

Motor Feedback:

CANopen RS232

Incremental Encoder Hall Sensors SSI Encoder

Digital I/Os:

4 x Input 2 x Output

Mechanical dimensions SD01-015





SD01-025/030





Ordering Information

| | | SD01 | - | 030 | 1D | А | В | CA | - | 00 |
|-----|---|------|---|-----|----|---|---|----|---|----|
| | SD01 Single-Axis Servo Drive | | | | | | | | | |
| | | | | | | | | | | |
| | Rating – Cont. Current, Peak Current | | | | | | | | | |
| 015 | 12/14.4 ^(*) Arms, 40 Arms peak @ 24 VDC | | | | | | | | | |
| 025 | 18/20 ^(*) Arms, 63 Arms peak @ 48 VDC | | | | | | | | | |
| 030 | 20/23 ^(*) Arms, 70 Arms peak @ 24 VDC | | | | | | | | | |
| ххх | Custom | | | | | | | | | |
| | Power | | | | | | | | | |
| 1D | Bus 20-60 VDC, Logic 24 VDC optional | | | | | | | | | |
| хх | Custom | | | | | | | | | |
| | Feedback | | | | | | | | | |
| AB | Incremental AB quadrature, index, Halls, 12 bit RS422 | | | | | | | | | |
| AS | Incremental AB quadrature, Halls, 12 bit RS422 and SSI (upcoming) | | | | | | | | | |
| хх | Custom | | | | | | | | | |
| | Communication | | | | | | | - | | |
| CA | CANopen | | | | | | | | | |
| хх | Custom | | | | | | | | | |
| | Options | | | | | | | | | |
| 000 | Standard | | | | | | | | | |
| 00M | Mating connector kit (P1, P2, P3, P4, C1) 025 and 030 only | | | | | | | | | |
| ххх | Custom | | | | | | | | | |
| | (*) with heat sink | | | | | | | | | |





Contact STXI Motion for optimal motion and automation solutions contact@stxim.com | www.stxim.com